



KPA **Mo**tion **D**evelopment **K**it (MoDK) enables the development of linear and coordinated motion applications for a hardware class on a specific OS.









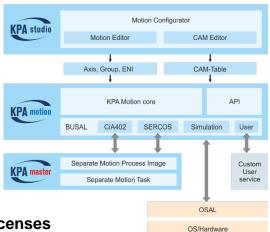


1 Introduction

Library for single- and multiple- axes control applicable in CNC solutions in terms of PLCopen standard.

1.1 Motion integration package (MoIP)

- MDK included (see MDK flyer for details)
- Motion "C/C++ API"
- Operation System Abstraction Layer (OSAL) (optionally in source code)
- Process filed bus Abstraction Layer (BUSAL) supporting CiA402, SERCOS and simulation (optionally in source code)
- More than 20 samples in source code and documents:
 - Motion architecture, white paper,
 - MoDK manuals, programmers guide,
 - API (Application Programming Interface) help



1.2 Motion Runtime package (MoRT) with licenses

- · Binaries and user manuals (development manuals included in MoIP)
- 2x KPA EtherCAT Master Standard Licenses (ETG 1500 "class A" master); 1x CoM and 10x LiM each
- 1x KPA EtherCAT Master Full (ETG 1500 "class A" including all FP and Extensions); 1x CoM and 10x LiM

1.3 KPA EtherCAT Studio executables

- KPA EtherCAT Studio Premium run-time including all plug-ins and user manuals for configuration and diagnostics of EtherCAT® networks.
- Motion Configurator
- 1x KPA EtherCAT Studio license

1.4 MDK/MoDK Tutorials

- How to use KPA EtherCAT Master for selected OS
- · How to use KPA EtherCAT Studio with Master for selected OS
- · How to configure EtherCAT network, DC, modules and other specifics

1.5 Simulation V-REP

Virtual robot experimentation platform

- V-REP Viewer
- · V-REP few sample models (further models are offered as service)

1.6 Support and Maintenance (S&M)

- Technical support and updates of Motion and EtherCAT Master/Studio for selected OS with access to Build Portal and Ticket System for one year.
- · Prolongation on annual base upon request

2 Runtime Software

- Trajectory generated online in one cycle
- Instantaneous reaction on events
- Jerk limited using spline interpolation
- · No transition (blending) window
- Cyclic synchronous position mode (no stop)
- Feed forward control of velocity and torque



2.1 KPA Motion Libraries

2.2 Linear Motion (LiM)

Applications: single axis drive control, e.g. pressing, drilling. Functionality:

- · Linear Movement of single axis
- Program Coordinate System (PCS)
- · Requirement: KPA Master Standard 1.5 or higher

2.3 Coordinated Motion (CoM)

Applications examples: bending, welding, drilling, milling. Functionality:

- · All LiM functionalities
- Multi-axes servo drive control with coordinated X, Y, Z axes
- Instantaneous transformations between PCS, MCS and ACS for 2D, 3D applications
- · Coordinated motion in cylinder and polar coordinates
- · Circular and helical motions

Requirement: KPA Master Standard 1.5 or higher

2.4 KPA Motion Configurator

Plugin to KPA Studio with two function groups:

Offline configuring

Grouping of axes, selection of drive profiles, setting of parameters, and mapping to process image

Online test

Controls with command and status for moving, homing and jogging

Requirement: KPA Studio Premium Version 2.0 or higher

3 Comparison of MoDK and MoDK trial

Item	Criteria	MoDK	MoDK trial
	Purpose	Development	Evaluation
1	Motion Integration Package (MoIP)	Yes	Yes
2	MoDK Tutorials	Yes	Yes
3	Runtime licenses (MoRT)	3 1)	Trial ²⁾
4	KPA EtherCAT Studio License	Premium unlimited	Premium 3 months
5	Support & Maintenance 3)	1 year	Startup support
6	Optional Build portal for OS	1 year	3 months

^{1) 1}x Full license and 2x Standard license.

 ${\tt MoDK\ and\ MoDK\ Trial\ are\ available\ through\ \underline{Customer\ portal}}\ and\ by\ contacting\ Sales: sales@hkaco.com$

Version 1.0







²⁾ Trial Master works for one hour in OPERATIONAL and cannot be licensed

³⁾ S&M-conditions you can find at our customer portal area